# IV B.TECH - I SEMESTER MACHINE DYNAMICS LAB

Course Code: ME7L2 Credits: 2

Lecture: -- Internal assessment: 25 marks
Practice: 3 periods/week Semester end examination: 50 marks

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#### **COURSE OBJECTIVES:**

• Determine the vibration parameters of a vibrating system

- Predict the radius of gyration and moment of inertia of vibrating system
- Verify the static and dynamic balancing
- Study the effect of gyroscopic couple and operations of robotic arm

## **COURSE OUTCOMES:**

Upon the completion of this course the student will be able to:

- 1. Evaluate the natural frequencies in different vibrating systems and effect of gyroscopic couple
- 2. Compute the radius of gyration & Moment of Inertia of oscillating part in vibration system
- 3. Apply the concepts of damping to determine damping coefficient
- 4. Measure the amplitude of vibration in damped and un damped vibrating system
- 5. Verify the static balancing and dynamic balancing
- 6. Implement the operations to manipulate the robot arm in industries

**Prerequisites:** Dynamics of Machinery

## Any 12 Experiments from following

## LIST OF EXPERIMENTS

- 1. Determination of Natural frequency of single mass, single helical spring system
- 2. Determination of Natural frequency of combination of springs springs in parallel or springs in series
- 3. Determination of Natural frequency of un damped torsional single rotor system
- 4. Determination of radius of gyration of a given compound pendulum
- 5. Determination of radius of gyration, moment of inertia bifilar suspension Method
- 6. To find Damping coefficient of torsional single rotor system
- 7. Determination of amplitude of vibration of damped vibrating system
- 8. Determination of amplitude of vibration of un damped vibrating system
- 9. Verify the Static balancing using steel balls
- 10. Verify the Dynamic balancing using steel balls
- 11. Whirling of shafts/ determination of critical speed with Rotors
- 12. Gyroscopic couple verification

- 13. Palletizing operation using Robot Arm
- 14. Direct Kinematic Analysis of Robot Arm

## Reference Books

1. Mechanical vibrations, (4th edition) by S.S.Rao Pearson education publications, Padparganj Delhi reprint 2004.